

## ***SOCKETS API Reference***

### **SOCKETS API Overview**

SOCKETS API is compatible with a wide range of third party TCP/IP applications, and contains descriptions for each of the supported functions. The function descriptions are preceded by introductory information that provides some background on the implementation of the SOCKETS API. The definitions and prototypes for the C environment are supplied in CAPI.H and COMPILER.H, while the implementation of the C interface in CAPI.C and \_CAPI.C. The SOCKETS API provides an interface to the socket, name resolution, ICMP ping, and kernel facilities provided by the Datalight DOS SOCKETS product. A *socket* is an end-point for a connection and is defined by the combination of a host address (also known as an IP address), a port number (or communicating process ID), and a transport protocol, such as UDP or TCP. Two connected SOCKETS using the same transport protocol define a connection. The API uses a socket handle, sometimes referred to as simply a socket. Previously, the socket handle has been referred to as a network descriptor. The socket handle is required by most function calls in order to access a connection. Two types of SOCKETS can be used: 1) a DOS compatible socket, previously referred to as a local network descriptor, which uses a DOS file handle, and 2) a normal socket (previously referred to as a global network descriptor) which does not use a DOS file handle. New designs should always use normal SOCKETS. A socket handle is obtained by calling the **GetSocket()** function. A socket handle can only be used for a single connection. When no longer required, such as when a connection has been closed, the socket handle must be released by calling **ReleaseSocket()**. DOS compatible socket handles are in the range 0 to 31, although 0 to 4 are normally be used by the C runtime for DOS files like **stdin** and **stdout**. Normal socket handles are positive numbers greater than 63.

### **Types of Service**

SOCKETS can be used with one of two service types:

- STREAM (using TCP).
- DATAGRAM (using UDP).

A stream connection provides for the bi-directional, reliable, sequenced, and unduplicated flow of data without record boundaries. No broadcast facilities can be used with a stream connection. A datagram connection supports bi-directional flow of data that is not guaranteed to be sequenced, reliable, or unduplicated. That is, a process receiving messages on a datagram socket may find messages duplicated, and, possibly, in an order different from the order in which it was sent. An important characteristic of a datagram connection is that record boundaries in data are preserved. Datagram connections closely model the facilities found in many contemporary packet switched networks such as Ethernet. Broadcast messages may be sent and received.

### **Establishing Remote Connections**

To establish a connection, one side (the server) must execute a **ListenSocket()** and the other side (the client) a **ConnectSocket()**.

A connection consists of the local socket / remote socket pair. It is therefore possible to have a connection within a single host as long as the local and remote *port* values differ. Each host in an IP network must have at least one host address also known as an IP address. When a host has more than one physical connection to an IP network, it may have more than one IP address. An IP address must be unique within a network. An IP address is 32 bits in length, a port number 16 bits. A value of zero means “any” while a binary value of all 1s means “all.” The latter value is used for broadcasting purposes. Using the NET\_ADDR structure conveys the addresses (host/port) to be used in a connection. The local host is not specified; it is implied. If a value of 0 is specified for *dwRemoteHost*, any remote IP address is accepted; and if a value of 0 is specified for a remote port, any remote port is accepted. This is normally the case when a server is listening for an incoming call. If a value of 0 is specified for *wLocalPort* in the case of a client calling **ConnectSocket()**, a unique port number is assigned by the TCP/IP stack.

## Using STREAM and DATAGRAM Services

When using the STREAM service (TCP), bi-directional data can be sent using the **WriteSocket()** function and received using the **ReadSocket()** function until one side performs an **EofSocket()** after which that side cannot send any more data, but can still receive data until the other side performs an **EofSocket()**, **AbortSocket()** or **ReleaseSocket()**. When using the DATAGRAM service, datagrams can be sent without first establishing a “connection”. In fact UDP provides a “connectionless” service although the connection paradigm is used. In addition to **ReadSocket()** and **WriteSocket()**, **ReadFromSocket()** and **WriteToSocket()** can be used. In this case **EofSocket()** has no meaning and returns an error.

### **Blocking and Non-blocking Operations**

The default behavior of socket functions is to block on an operation and only return when the operation has completed. For example, the **ConnectSocket()** function only returns after the connection has been performed or an error is encountered. This behavior applies to most socket function calls, such as **ReadSocket()** and even **WriteSocket()**, and especially on STREAM connections. In many, if not most applications, this behavior is unacceptable in the single-threaded DOS environment and must be modified. This modification can be accomplished in by either::

1. By specifying the NET\_FLG\_NON\_BLOCKING flag on **ReadSocket()** and **WriteSocket()** calls or
2. By making all operations on a socket non-blocking by calling **SetSocketOption()** with the NET\_OPT\_NON\_BLOCKING option.

If a non-blocking operation is performed, the function always returns immediately. If the function could not complete without blocking, an error is returned with *SocketsErrNo* containing ERR\_WOULD\_BLOCK. This error should be regarded as a recoverable error and the operation should be retried, preferably at some later time.

### **Blocking Operations with Timeouts**

A possible alternative to using non-blocking operations is to use blocking operations with timeouts. This is done by calling **SetSocketOption()** with the NET\_OPT\_TIMEOUT option, in which case the function blocks for the specified time, or until completed, whichever occurs first. If the specified timeout occurs first, an error is returned with *SocketsErrNo* containing ERR\_TIMEOUT and the operation must be retried. Use non-blocking operations rather than timeouts, although they may be somewhat more difficult to implement.

### **Asynchronous Notifications/Callbacks**

Asynchronous notifications or callbacks can be used in cases where the polling implied by non-blocking operation is not desirable, when immediate action is required, when a network operation completes, or when a SOCKETS application runs as a TSR. However, such notifications may be difficult to use and the programmer must be careful to avoid system crashes resulting from improper use. The **SetAsyncNotification()** function sets functions to be called on specific events, such as opening and closing of STREAM connections and receiving data on STREAM and DATAGRAM connections. The **SetAlarm()** function is called to set a function to be called when a timer expires. Asynchronous notifications are disabled by the **DisableAsyncNotification()** function and enabled by the **EnableAsyncNotification()** function. For more details on the operation and pitfalls associated with callbacks, refer to the description of **SetAsyncNotification()**. **ResolveName()**, **GetDCSocket()**, **ConvertDCSocket()**, **ReleaseSocket()** on a DC socket, **ConnectSocket()** with a socket value of -1, and **ListenSocket()** with a socket value of -1 all call DOS. For this reason, these functions should not be called from within a callback or an interrupt service routine.

### **IP Address Resolution**

Two functions are provided for IP address resolution. **ParseAddress()** converts a dotted decimal address to a 32-bit IP address.

**ResolveName()** converts a symbolic host name to a 32-bit IP address using a host table lookup; if that fails and a domain server is configured, then to a DNS lookup. **ResolveName()** calls DOS to perform a host table lookup and always blocks while doing a DNS lookup.

### **Obtaining SOCKETS Kernel Information**

You can obtain information on the SOCKETS TCP/IP kernel by the **GetKernelInformation()**, **GetVersion()** and **GetKernelConfig()** functions. You can unload the kernel by **ShutDownNet()**.

### **Error Reporting**

In general, the C functions implementing the compatible API return a value of -1 if the return type is **int** and an error is encountered, in which case, the actual error code is returned in a common variable *SocketsErrNo*. In some cases, *iSubNetErrNo* is also used. Any API call may fail with an error code of **ERR\_API\_NOT\_LOADED** or **ERR\_RE\_ENTRY**. **ERR\_RE\_ENTRY** is returned when the SOCKETS kernel has been interrupted. This condition can occur only when the API is called from an interrupt service routine. Programs designed for this type of operation, such as TSR programs activated by a real time clock interrupt, should be coded to handle this error by re-trying the function at a later stage.

### **Low Level Interface to Compatible API**

Low level functions to access the Compatible API may be used. In this case, the compatible API is called by setting up the CPU registers and executing a software interrupt. The default interrupt is 61 hexadecimal, but may be relocated when SOCKETS is loaded. If the actual interrupt is not known, a search may be performed for it. Refer to the source file **CAPI.C** for more details. On entry, **AH** contains a number specifying the function to perform. On return, the carry flag is cleared on success and set on failure.

### **Alternatives to the Compatible API**

Two additional programming interfaces are available for use with SOCKETS. The first is an earlier revision of CAPI, now called **CAPIOLD**. This interface is provided to maintain compatibility with applications developed for SOCKETS 1.0. It is superseded by CAPI, which is better-documented and easier to use. Both CAPI and CAPIOLD rely on an internal array of socket descriptors, which must be configured at compile-time. This can use excess memory if your application rarely uses a large number of SOCKETS simultaneously. In addition, it is advised that these APIs do not deal well with mixing both blocking and non-blocking SOCKETS in one application. The second interface is called **APIC**, and is more robust for TSR and server applications. It is a more natural stack interface, which hides fewer details from the programmer. As a result, it is more difficult to work with, and should be used only when its extended features and lowered memory footprint are required. Due to the low popularity of this interface, documentation is provided only inside the **APIC.C** and **APIC.H** source files.

### **Porting for Compilers**

Compiler specific functions have been written into the **compiler.h**. Modifications for compilers other than the supplied Borland BC5.2 compiler and any listed within **compiler.h** need to happen within this file. Datalight will offer any assistance we can to help with porting to other compilers but our expertise exists within the supplied Borland compiler.

### **Usage Notes**

Please refer to the make file provided within the **SOCKETS\EXAMPLES** directory for command line compiler options.

### **Function Reference**

The following sections describe the individual functions of the SOCKETS API.

### **DisableAsyncNotification**

The **DisableAsyncNotification()** function disables Asynchronous notifications (callbacks).

#### **C syntax**

```
int DisableAsyncNotification(void);
```

#### **Return value**

Returns -1 on error with *SocketsErrNo* containing the error. Returns previous state on success, 0 for disabled, 1 for enabled.

#### **Low level calling parameter**

AH DISABLE\_ASYNC\_NOTIFICATION (0x11)

#### **Low level return parameter**

AX = previous state, 0 = disabled, 1 = enabled

### **EnableAsyncNotification**

The **EnableAsyncNotification()** function enables asynchronous notifications (callbacks).

#### **C syntax**

```
int EnableAsyncNotification(void);
```

#### **Return value**

Returns -1 on error with *SocketsErrNo* containing the error. Returns previous state on success, 0 for disabled, 1 for enabled.

#### **Low level calling parameter**

AH ENABLE\_ASYNC\_NOTIFICATION (0x12)

#### **Low level return parameter**

AX = previous state, 0 = disabled, 1 = enabled.

### **GetAddress**

The **GetAddress()** function gets the local IP address of a connection. In the case of a single interface host, this is the IP address of the host. In the case of more than one interface, the IP address of the interface being used to route the traffic for the specific connection is given.

#### **C syntax**

```
DWORD GetAddress(int iSocket);
```

#### **Parameter**

*iSocket*

Socket handle for the connection.

#### **Return value**

Returns IP address on success. Returns 0L on error with *SocketsErrNo* containing the error.

#### **Low level calling parameters**

AH GET\_ADDRESS (0x05)

BX Socket

#### **Low level return parameters**

AX:DX = IP address of this host. AX:DX = 0:0 on error.

### **GetPeerAddress**

The **GetPeerAddress()** function gets peer address information on a connected socket.

#### **C syntax**

int **GetPeerAddress**(int *iSocket*, NET\_ADDR *\*pAddr*);

### Options

*iSocket*

Socket handle for the connection.

*pAddr*

Pointer to NET\_ADDR structure to receive information.

### Return values

Returns 0 and NET\_ADDR structure filled in on success. Returns -1 with *SocketsErrNo* containing the error on failure.

### Low level calling parameters

AH GET\_PEER\_ADDRESS (0x16).

BX Socket.

DS:DX Pointer to NET\_ADDR address structure.

### Low level return parameters

If carry flag is clear, the address structure is filled in

If carry flag is set, AX = error code

### GetKernelInformation

The **GetKernelInformation**() function gets specified information from the kernel.

### C syntax

```
int GetKernelInformation(int iReserved, BYTE bCode, BYTE bDevID, void *pData, WORD  
*pwSize);
```

### Options

*iReserved*

Reserved value, set to zero.

*bCode*

Code specifying kernel info to retrieve:

K\_INF\_HOST\_TABLE Gets name of file containing host table.

K\_INF\_DNS\_SERVERS Gets IP addresses of DNS Servers.

K\_INF\_TCP\_CONS Gets number of Sockets (DC + normal).

K\_INF\_BCAST\_ADDR Gets broadcast IP address.

K\_INF\_IP\_ADDR Gets IP address of first interface.

K\_INF\_SUBNET\_MASK Gets netmask of first interface.

*pData*

Pointer to data area to receive kernel information.

*pwSize*

Pointer to WORD containing length of data area.

### Return values

On success returns 0 with data area and size word filled in. Returns -1 with *SocketsErrNo* containing the error on failure.

### Low level calling parameters

AH GET\_KERNEL\_INFO (0x02)

DS:SI Pointer to data area to receive kernel information.

ES:DI Pointer to WORD containing length of data area.

DH Code specifying kernel info to retrieve.

K\_INF\_HOST\_TABLE Gets name of file containing host table.

K\_INF\_DNS\_SERVERS Gets IP addresses of DNS Servers.

K\_INF\_TCP\_CONS Gets number of Sockets (DC + normal).

K\_INF\_BCAST\_ADDR Gets broadcast IP address.

K\_INF\_IP\_ADDR Gets IP address of first interface.

K\_INF\_SUBNET\_MASK Gets netmask of first interface.

### Low level return parameters

If no error, data area is filled in as well as the size word.

### GetVersion

The **GetVersion()** function gets version number of the Compatible API.

### C syntax

```
int GetVersion(void);
```

### Return value

Returns 0x214 on success, -1 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH GET\_NET\_VERSION (0x0F).

### Low level return parameters

AX = 0x214112 Chapter 8, SOCKETS API Reference

### ICMPPing

The **ICMPPing()** function sends an ICMP ping (echo request) and waits until a response is received or for six seconds if no response is received. **ICMPPing()** is always a blocking function.

### C syntax

```
int ICMPPing(DWORD dwHost, int iLength);
```

### Options

*dwHost*

IP address of host to ping.

*iLength*

Number of data bytes in ping request.

### Return value

Returns 0 on success, -1 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH ICMP\_PING (0x30).

CX number of data bytes in ping request.

DX:BX IP address of host to ping.

### Low level return parameters

If carry flag is set, AX = error code.

## **IsSocket**

The **IsSocket()** function checks a DOS compatible socket for validity.

### **C syntax**

```
int IsSocket(int iSocket);
```

### **Parameter**

*iSocket*

DOS Compatible socket handle for the connection.

### **Return value**

Returns 0 on success, -1 on failure with *SocketsErrNo* containing the error code.

### **Low level calling parameters**

AH IS\_SOCKET (0x0D).

BX Local socket.

### **Low level return parameters**

Carry flag clear if valid.

Carry flag set if not valid, AX = error code.

## **GetDCSocket**

The **GetDCSocket()** function gets a DOS-compatible socket handle. This function calls DOS to open a DOS file handle.

### **C syntax**

```
int GetDCSocket(void);
```

### **Return value**

Returns socket handle on success, -1 on failure with *SocketsErrNo* containing the error code.

### **Low level calling parameters**

AH GET\_DC\_SOCKET (0x22).

### **Low level return parameters**

If carry flag is clear, AX = Socket.

If carry flag is set, AX = error code.

## **GetSocket**

The **GetSocket()** function gets a socket handle.

### **C syntax**

```
int GetSocket(void);
```

### **Return value**

Returns socket handle on success, -1 on failure with *SocketsErrNo* containing the error code.

### **Low level calling parameters**

AH GET\_SOCKET (0x29).

### **Low level return parameters**

If carry flag is clear, AX = Socket.

If carry flag is set, AX = error code.

## **GetKernelConfig**

The **GetKernelConfig()** function gets the kernel configuration.

### C syntax

```
int GetKernelConfig(KERNEL_CONFIG *psKc);
```

### Parameter

*psKc*

Pointer to KERNEL\_CONFIG structure.

bKMaxTcp Number of TCP sockets allowed.

BKMaxUdp Number of UDP sockets allowed.

bKMaxIp Number of IP sockets allowed (0).

bKMaxRaw Number of RAW\_NET sockets allowed (0).

bKActTcp Number of TCP sockets in use.

bKActUdp Number of UDP sockets in use.

bKActIp Number of IP sockets in use (0).

bKActRaw Number of RAW\_NET sockets in use (0).

wKActDCS Number of active Dos Compatible Sockets.

wKActSoc Number of active normal Sockets.

bKMaxLnh Maximum header on an attached network.

bKMaxLnt Maximum trailer on an attached network.

bKLBUF\_SIZE Size of a large packet buffer.

bKNnet Number of network interfaces attached.

dwKCTicks Milliseconds since kernel started.

dwKBroadcast IP broadcast address in use.

### Return value

Returns 0 on success with KERNEL\_CONFIG structure filled in, -1 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH GET\_KERNEL\_CONFIG (0x2A).

DS:SI pointer to kernel\_conf structure.

### Return

KERNEL\_CONF structure filled in.

### ConvertDCSocket

The **ConvertDCSocket()** function changes a DOS compatible socket handle into a normal socket handle. This function calls DOS to close a DOS file handle.

### C syntax

```
int ConvertDCSocket(int iSocket);
```

### Parameter

*iSocket*

DOS Compatible socket handle.

### Return value

Returns socket handle on success, -1 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH CONVERT\_DC\_SOCKET (0x07).

BX Local socket.

### Low level return parameters

AX = Global socket if no error.

### GetNetInfo

The **GetNetInfo()** function gets information about the network.

### C syntax

```
int GetNetInfo(int iSocket, NET_INFO *psNI);
```

### Parameter

*iSocket*

Socket handle for the connection.

*psNI*

Pointer to NET\_INFO structure. The following members of NET\_INFO are obtained:

DwIPAddress

dwIPSubnet

iUp

iLanLen

pLanAddr

### Return value

Returns 0 with NET\_INFO structure filled in on success, -1 on failure with *SocketsErrNo*

containing the error code.

### Low level calling parameters

AH GET\_NET\_INFO (0x06).

DS:SI Pointer to netinfo structure.

### Low-level return

netinfo structure filled in.

### ConnectSocket

The **ConnectSocket()** function makes a network connection. If *iSocket* is specified as -1, a DOS compatible socket is assigned.

In this case only, DOS is called to open a file handle. If *iSocket* specifies a non-blocking socket or *iType* specifies a

DATAGRAM connection, this call returns immediately. In the case of a STREAM connection, the connection may not yet be

established. **ReadSocket()** can be used to test for connection establishment. As long as **ReadSocket()** returns an

ERR\_NOT\_ESTAB code, the connection is not established. A good return or an error return with ERR\_WOULD\_BLOCK

indicates an established connection. A more complex method uses **SetAsyncNotify()** with NET\_AS\_OPEN to test for connection

establishment. NET\_AS\_ERROR should also be set to be notified of a failed open attempt.

### C syntax

```
int ConnectSocket(int iSocket, int iType, NET_ADDR *psAddr);
```

### Parameter

*iSocket*

Socket handle for the connection.

*iType*

Type of connection: STREAM or DATAGRAM.

*psAddr*

Pointer to NET\_ADDR structure.

#### **Return value**

Returns socket on success, -1 on failure with SocketsErrNo containing the error code.

#### **Low level calling parameters**

AH CONNECT\_SOCKET (0x13).

BX Socket.

DX Connection mode: Stream or DataGram.

DS:SI Pointer to NET\_ADDR address structure.

#### **Low level return parameters**

If carry flag clear, initiated OK, AX = Socket.

If carry flag set, AX = error code.

#### **ListenSocket**

The **ListenSocket()** function listens for a network connection. If *iSocket* is specified as -1, a DOS compatible socket is assigned.

In this case only, DOS is called to open a file handle. If *iSocket* specifies a non-blocking socket or *iType* specifies a

DATAGRAM connection, this call returns immediately. In the case of a STREAM connection, the connection may not be

established yet. **ReadSocket()** can be used to test for connection establishment. As long as **ReadSocket()** returns an

ERR\_NOT\_ESTAB code, the connection is not established. A good return or an error return with ERR\_WOULD\_BLOCK

indicates connection establishment. A more complex method is to use **SetAsyncNotify()** with NET\_AS\_OPEN to test for

connection establishment. NET\_AS\_ERROR should also be set to be notified of a failed open attempt.

#### **C syntax**

```
int ListenSocket(int iSocket, int iType, NET_ADDR *psAddr);
```

#### **Parameter**

*iSocket*

Socket handle for the connection.

*iType*

Type of connection: STREAM or DataGram.

*psAddr*

Pointer to NET\_ADDR structure.

#### **Return value**

Returns socket handle on success, -1 on failure with SocketsErrNo containing the error code.

#### **Low level calling parameters**

AH LISTEN\_SOCKET (0x23).

BX Socket.

DX Connection mode: STREAM or DataGram.

DS:SI Pointer to NET\_ADDR address structure.

#### **Low level return parameters**

If carry flag clear, initiated OK, AX = Socket.

If carry flag set, AX = error code.

### **SelectSocket**

The **SelectSocket()** function tests all DOS compatible sockets for data availability and readiness to write. A 32-bit DWORD representing 32 DC sockets is filled in for each socket with receive data, and another 32-bit DWORD for DC sockets ready for writing. The least-significant bit represents the socket with value 0 and the most-significant bit represents the socket with value 31. Bits representing unused sockets are left unchanged.

#### **C syntax**

int **SelectSocket**(int *iMaxid*, long *\*pllflags*, long *\*ploflags*);

#### **Options**

*iMaxid*

Number of sockets to test.

*pllflags*

Pointer to input flags indicating receive data availability.

*ploflags*

Pointer to output flags indicating readiness to write.

#### **Return value**

Returns 0 on success with *\*pllflags* and *\*ploflags* filled in with current status, -1 on failure with `SocketsErrNo` containing the error code.

#### **Low level calling parameters**

AH `SELECT_SOCKET` (0x0e).

BX Number of sockets to test.

DS:DX Pointer to DWORD for data availability.

ES:DI Pointer to DWORD for readiness to write.

#### **Low level return parameters**

Both DWORDs updated with current status.

### **ReadSocket**

The **ReadSocket()** function reads from the network using a socket. **ReadSocket()** returns as soon as any non-zero amount of data is available, regardless of the blocking state. If the operation is non-blocking, either by having used **SetSocketOption()** with the `NET_OPT_NON_BLOCKING` option or specifying *wFlags* with `NET_FLG_NON_BLOCKING`, **ReadSocket()** returns immediately with the count of available data or an error of `ERR_WOULD_BLOCK`. With a `STREAM` (TCP) socket, record boundaries do not exist and any amount of data can be read at any time regardless of the way it was sent by the peer. No data is truncated or lost even if more data than the buffer size is available. What is not returned on one call, is returned on subsequent calls. If a `NULL` buffer is specified, the number of bytes on the receive queue is returned. In the case of a `DataGram` (UDP) socket, the entire datagram is returned in one call, unless the buffer is too small in which case the data is truncated, thereby preserving record boundaries. Truncated data is lost. If data is available and both the `NET_FLG_PEEK` and `NET_FLG_NON_BLOCKING` flags are specified, the number of datagrams on the receive queue is returned. If data is available and `NET_FLG_PEEK` is set and a `NULL` buffer is specified, the number of bytes in the next datagram is returned.

## C syntax

```
int ReadSocket(int iSocket, char *pcBuf, WORD wLen, NET_ADDR *psFrom, WORD  
wFlags);
```

## Options

*iSocket*

Socket handle for the connection.

*pcBuf*

Pointer to buffer to receive data.

*wLen*

Length of buffer, i.e. maximum number of bytes to read.

*psFrom*

Pointer to NET\_ADDR structure to receive address information about local and remote ports and remote IP address.

*wFlags*

Flags governing operation. Any combination of:

NET\_FLG\_PEEK Don't dequeue data.

NET\_FLG\_NON\_BLOCKING Don't block.

## Return value

Returns number of bytes read on success, -1 on failure with *SocketsErrNo* containing the error code. A return code of 0 indicates that the peer has closed the connection.

**Note:** If blocking is disabled, a failure with an error code of ERR\_WOULD\_BLOCK is completely normal and only means that no data is currently available.

## Low level calling parameters

AH READ\_SOCKET (0x1b).

BX Socket.

CX Maximum number of bytes to read.

DX Flags - any combination of.

NET\_FLG\_PEEK: Don't dequeue data.

NET\_FLG\_NON\_BLOCKING: Don't block.

DS:SI Pointer to buffer to read into.

ES:DI Pointer to NET\_ADDR address structure.

## Low level return parameters

If carry flag is clear, AX = CX = number of bytes read.

If carry flag is set, AX = error code.

## ReadFromSocket

The **ReadFromSocket()** function reads from the network using a socket and is only intended to be used on Datagram sockets.

All datagrams from the IP address and port matching the values in the NET\_ADDR structure are returned while others are discarded. A zero value for *dwRemoteHost* is used as a wildcard to receive from any host and a zero value for *wRemotePort* is used as a wildcard to receive from any port. The local port, *wLocalPort*, can not be specified as zero. In other respects

**ReadFromSocket()** behaves the same as **ReadSocket()**.

## C syntax

```
int ReadFromSocket(int iSocket, char *pcBuf, WORD wLen, NET_ADDR *psFrom, WORD wFlags);
```

## Options

*iSocket*

Socket for the connection.

*pcBuf*

Pointer to buffer to receive data.

*wLen*

Length of buffer, i.e. maximum number of bytes to read.

*psFrom*

Pointer to NET\_ADDR structure to receive address information about local and remote ports and remote IP address.

*wFlags*

Flags governing operation. Any combination of:

NET\_FLG\_PEEK Don't dequeue data.

NET\_FLG\_NON\_BLOCKING Don't block.

## Return value

Returns number of bytes read on success, -1 on failure with *SocketsErrNo* containing the error code. A return code of 0 indicates that the peer has closed the connection. Note the following anomaly: If blocking is disabled, a failure with an error code of ErrWouldBlock is completely normal and only means that no data is currently available.

## Low level calling parameters

AH READ\_FROM\_SOCKET (0x1d).

BX Socket.

CX Maximum number of bytes to read.

DX Flags - any combination of.

NET\_FLG\_PEEK:- Don't dequeue data.

NET\_FLG\_NON\_BLOCKING:- Don't block.

DS:SI Pointer to buffer to read into.

ES:DI Pointer to NET\_ADDR address structure.

## Low level return parameters

If carry flag is clear, AX = CX = number of bytes read.

If carry flag is set, AX = error code.

## WriteSocket

The **WriteSocket()** function writes to the network using a socket.

## C syntax

```
int WriteSocket(int iSocket, char *pcBuf, WORD wLen, WORD wFlags);
```

## Parameter

*iSocket*

Socket handle for the connection.

*pcBuf*

Pointer to buffer to containing send data.

*wLen*

Length of buffer, i.e. number of bytes to write.

*wFlags*

Flags governing operation; can be any combination of:

NET\_FLG\_OOB Send out of band data (TCP only).

NET\_FLG\_PUSH Disregard Nagle heuristic (TCP only).

NET\_FLG\_NON\_BLOCKING Don't block.

NET\_FLG\_BROADCAST Broadcast data (UDP only).

NET\_FLG\_MC\_NOECHO Suppress the local echo of a multicast datagram.

### **Return value**

Returns number of bytes written on success, -1 on failure with *SocketsErrNo* containing the error code. The number of bytes actually written on a non-blocking write, can be less than *wLen*. In such a case, the writing of the unwritten bytes must be retried, preferably after some delay.

### **Low level calling parameters**

AH WRITE\_SOCKET (0x1a).

BX Socket.

CX Byte count.

DX Flags - any combination of the following:

NET\_FLG\_OOB:- Send out of band data (TCP only).

NET\_FLG\_PUSH:- Disregard Nagle heuristic (TCP only).

NET\_FLG\_NON\_BLOCKING:- Don't block.

NET\_FLG\_BROADCAST:- Broadcast data (UDP only).

DS:SI Pointer to buffer to write.

### **Low level return parameters**

If carry flag is clear, AX = number of bytes sent.

If carry flag is set, AX = error code.

### **WriteToSocket**

The **WriteToSocket()** function writes to the network using a network address (UDP only).

### **C syntax**

```
int WriteToSocket(int iSocket, char *pcBuf, WORD wLen, NET_ADDR *psTo, WORD  
wFlags);
```

### **Options**

*iSocket*

Socket handle for the connection.

*pcBuf*

Pointer to buffer containing send data.

*wLen*

Length of buffer, i.e. number of bytes to write.

*psTo*

Pointer to NET\_ADDR structure containing local port to write from and remote port and IP address to write to.

*wFlags*

Flags governing operation. Any combination of:

NET\_FLG\_NON\_BLOCKING Don't block.

NET\_FLG\_BROADCAST Broadcast data (UDP only).

#### **Return value**

Returns number of bytes written on success, -1 on failure with *SocketsErrNo* containing the error code.

#### **Low level calling parameters**

AH WRITE\_TO\_SOCKET (0x1C).

BX Socket.

CX Byte count.

DX Flags:

NET\_FLG\_NON\_BLOCKING:- Don't block

NET\_FLG\_BROADCAST:- Broadcast data (UDP only).

DS:SI Pointer to buffer to write.

ES:DI Pointer to NET\_ADDR address structure.

#### **Low level return parameters**

If carry flag is clear, AX = number of bytes sent.

If carry flag is set, AX = error code.

#### **EofSocket**

The **EofSocket()** function closes the STREAM (TCP) connection (sends a FIN). After **EofSocket()** has been called, no

**WriteSocket()** calls may be made. The socket remains open for reading until the peer closes the connection.

#### **C syntax**

```
int EofSocket(int iSocket);
```

#### **Parameter**

*iSocket*

Socket handle for the connection.

#### **Return value**

Returns 0 on success, -1 on failure with *SocketsErrNo* containing the error code.

#### **Low level calling parameters**

AH EOF\_SOCKET (0x18)

BX Socket

#### **Low level return parameters**

If carry flag is set, AX = error code.

#### **FlushSocket**

The **FlushSocket()** function flushes any output data still queued for a TCP connection.

### C syntax

```
int FlushSocket(int iSocket);
```

### Parameter

*iSocket*

Socket handle for the connection.

### Return value

Returns 0 on success, -1 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH FLUSH\_SOCKET (0x1e)

BX Socket

### Low level return parameters

If carry flag set, AX = error code.

### ReleaseSocket

The **ReleaseSocket()** function closes the connection and releases all resources. On a STREAM (TCP) connection, this function should only be called after the connection has been closed from both sides otherwise a reset (ungraceful close) can result.

### C syntax

```
int ReleaseSocket(int iSocket);
```

### Parameter

*iSocket*

Socket handle for the connection.

### Return value

Returns socket handle on success, -1 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH RELEASE\_SOCKET (0x08).

BX Socket.

### Low level return parameters

AX = error code if carry flag is set

### ReleaseDCSockets

The **ReleaseDCSockets** function closes all connections and releases all resources associated with DOS compatible sockets.

### C syntax

```
int ReleaseDCSockets(void);
```

### Return value

Returns 0 on success, -1 on failure with *SocketsErrNo* containing the error code.

### C syntax

```
int ReleaseDCSockets(void);
```

### Low level calling parameters

AH RELEASE\_DC\_SOCKETS (0x09).

### Low level return parameters

AX = error code if carry flag is set.

### **AbortSocket**

The **AbortSocket()** function aborts the network connection and releases all resources. This function causes an unpredictable close (reset) on a STREAM connection.

#### **C syntax**

```
int AbortSocket(int iSocket);
```

#### **Parameter**

*iSocket*

Socket handle for the connection.

#### **Return value**

Returns socket handle on success, -1 on failure with *SocketsErrNo* containing the error code.

#### **Low level calling parameters**

AH ABORT\_SOCKET (0x19).

BX Socket.

#### **Low level return parameters**

If carry flag is set, AX = error code.

### **AbortDCSockets**

The **AbortDCSockets** function aborts all DOS compatible socket connections.

#### **C syntax**

```
int AbortDCSockets(void);
```

#### **Return value**

Returns 0 on success, -1 on failure with *SocketsErrNo* containing the error code.

#### **Low level calling parameters**

AH ABORT\_DC\_SOCKETS (0x24).

#### **Low level return parameters**

If carry flag is set, AX = error code.

### **ShutDownNet**

The **ShutDownNet()** function shuts down the network and unloads the SOCKETS TCP/IP kernel.

#### **C syntax**

```
int ShutDownNet(void);
```

#### **Return value**

Returns 0 on success, -1 on failure with *SocketsErrNo* containing the error code.

#### **Low level calling parameters**

AH SHUT\_DOWN\_NET (0x10).

#### **Low level return parameters**

None.

### **SetAlarm**

The **SetAlarm()** function sets an alarm timer.

#### **C syntax**

```
int SetAlarm(int iSocket, DWORD dwTime, int (far *lpHandler)(), DWORD dwHint);
```

## Options

*iSocket*

Socket handle for the connection.

*dwTime*

Timer delay in milliseconds.

*lpHandler*

Far address of alarm callback. See the description of **SetAsyncNotification()** for the format of the callback function.

*dwHint*

Argument to be passed to callback function.

## Return value

Returns socket handle on success, -1 on failure with *SocketsErrNo* containing the error code.

## Low level calling parameters

AH SET\_ALARM (0x2bB.

BX Socket.

CX:DX Timer delay in milliseconds.

DS:SI Address of alarm callback.

ES:DI Argument to be passed to callback.

## Low level return parameters

If carry flag is set, AX = error code

See the description of SET\_ASYNC\_NOTIFICATION for the callback function.

## SetAsyncNotification

The **SetAsyncNotification()** function sets an asynchronous notification (callback) for a specific event.

## C syntax

```
int far *SetAsyncNotification(int iSocket, int iEvent, int (far *lpHandler)(),DWORD dwHint);
```

## Parameter

*iSocket*

Socket handle for the connection.

*iEvent*

Event which is being set:

NET\_AS\_OPEN Connection has opened.

NET\_AS\_RCV Data has been received.

NET\_AS\_XMT Ready to transmit.

NET\_AS\_FCLOSE Peer has closed connection.

NET\_AS\_CLOSE Connection has been closed.

NET\_AS\_ERROR Connection has been reset.

*lpHandler*

Far address of callback function.

*dwHint*

Argument to be passed to callback function

The handler is not compatible with C calling conventions but is called by a far call with the following parameters:

BX = Socket handle.

CX = Event.

ES:DI = dwHint argument passed to SetAsyncNotification() or SetAlarm().

DS:DX = SI:DX = variable argument depending on event:

NET\_AS\_OPEN

NET\_AS\_CLOSE Pointer to NET\_ADDR address structure.

NET\_AS\_FCLOSE

NET\_AS\_RCV

NET\_AS\_ALARM Zero.

NET\_AS\_XMT Byte count which can be sent without blocking.

NET\_AS\_ERROR Error code -ERR\_TERMINATING, ERR\_TIME\_OUT or

ERR\_RESET.

Other CAPI functions may be called in the callback, with the exception of ResolveName() which may call DOS. The callback is not compatible with C argument-passing conventions and some care must be taken. Some CPU register manipulation is required. This can be done by referencing CPU registers, such as \_BX, or by means of assembler instructions. In the callback, the stack is supplied by SOCKETS and may be quite small depending on the /s= command line option when loading SOCKETS. The stack segment is obviously not equal to the data segment, which can cause problems when the Tiny, Small or Medium memory model is used. The simplest way to overcome the problem is to use the Compact, Large or Huge memory model. Other options - use the DS != SS compiler option or do a stack switch to a data segment stack. If the callback is written in C or C++, the \_loads modifier can be used to set the data segment to that of the module, which destroys the DS used for the variable argument. (This is why DS == SI on entry for SOCKETS version 1.04 and later.) An alternate method is to use the argument passed to SetAsyncNotification() in ES:DI as a pointer to a structure that is accessible from both the main code and the callback. If DS is not set to the data segment of the module, then the functions in CAPI.C do not work: Don't use them in the callback. The callback will probably be performed at interrupt time with no guarantee of reentry to DOS. Do not use any function, such as putchar() or printf(), in the callback which may cause DOS to be called. It is good programming practice to do as little as possible in the callback. The setting of event flags that trigger an operation at a more stable time is recommended. Callback functions do not nest. The callback function is not called while a callback is still in progress, even if other CAPI functions are called. To alleviate the problems in items 2, 3 and 4 above, a handler is provided in CAPI.C that uses the dwHint parameter to pass the address of a C-compatible handler, with a stack that is also C-compatible. This handler is named AsyncNotificationHandler. A user handler named MyHandler below, is called in the normal way with a stack of 500 bytes long. Changing the HANDLER\_STACK\_SIZE constant in CAPI.C can set the stack size value.

```
int far MyHandler(int iSocket, int iEvent, DWORD dwArg);
```

```
SetAsyncNotification(iSocket, iEvent, AsyncNotificationHandler, (DWORD)MyHandler);
```

#### **Return value**

Returns pointer to the previous callback handler on success, -1 on failure with *SocketsErrNo* containing the error code.

#### **Low level calling parameters**

AH SET\_ASYNC\_NOTIFICATION (0x1F).

BX Socket.

CX Event:

NET\_AS\_OPEN: Connection has opened.

NET\_AS\_RCV: Data has been received.

NET\_AS\_XMT: Ready to transmit.

NET\_AS\_FCLOSE: Peer has closed connection.

NET\_AS\_CLOSE: Connection has been closed.

NET\_AS\_ERROR: Connection has been reset.

DS:DX Address of handler.

ES:DI Argument passed to handler.

### Low level return parameters

If carry flag is set, AX = error code, else address of previous handler is returned in DX:AX.

### ResolveName

The **ResolveName()** function resolves IP address from symbolic name.

### C syntax

```
DWORD ResolveName(char *pszName, char *pcCname, int iCnameLen);
```

### Options

*pszName*

Pointer to string containing symbolic name.

*pcCname*

Pointer to buffer to receive canonical name.

*ICnameLen*

Length of buffer pointed to by *pcName*.

### Return value

Returns IP address on success, 0 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH RESOLVE\_NAME (0x54).

CX Size of buffer to receive canonical name.

DS:DX Pointer to string containing symbolic name.

ES:DI Pointer to buffer to receive canonical name.

### Low level return parameters

If carry flag is clear, AX:DX = IP address.

If carry flag is set, AX = error code.

### ParseAddress

The **ParseAddress()** function gets an IP address from dotted decimal addresses.

### C syntax

```
DWORD ParseAddress(char *pszName);
```

### Parameter

*pszName*

Pointer to string containing dotted decimal address.

### Return value

Returns IP address on success, 0 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH PARSE\_ADDRESS (0x50).

DS:DX Pointer to dotted decimal string.

### Low level return parameters

AX:DX = IP address.

### SetSocketOption

The **SetSocketOption()** function sets an option on the socket.

### C syntax

```
int SetSocketOption(int iSocket, int iLevel, int iOption, DWORD dwOptionValue, int iLen);
```

### Options

*iSocket*

Socket handle for the connection.

*iLevel*

Level of option. This value is ignored.

*iOption*

Option to set.

NET\_OPT\_NON\_BLOCKING Set blocking off if *dwOptionValue* is non-zero.

NET\_OPT\_TIMEOUT Set the timeout to *dwOptionValue* milliseconds. Turn off timeout if *dwOptionValue* is zero.

NET\_OPT\_WAIT\_FLUSH Wait for flush if *dwOptionValue* is non-zero.

*dwOptionValue*

Option value.

*iLen*

Length of *dwOptionValue*, 4 in all cases.

### Return value

Returns global socket on success, -1 on failure with *SocketsErrNo* containing the error code.

### Low level calling parameters

AH SET\_OPTION (0x20).

BX Socket.

DS:DX Value of option.

DI Option:

NET\_OPT\_NON\_BLOCKING:- Set blocking off if *dwOptionValue* is non-zero.

NET\_OPT\_TIMEOUT:- Set the timeout to *dwOptionValue* milliseconds. Turn off timeout if *dwOptionValue* is zero.

NET\_OPT\_WAIT\_FLUSH:Wait for flush if *dwOptionValue* is non-zero.

### Low level return parameters

If carry flag is set, AX = error code.

### **JoinGroup**

The **JoinGroup()** function causes SOCKETS to join a multicast group.

#### **C syntax**

```
int JoinGroup(DWORD dwGroupAddress, DWORD dwIPAddress);
```

#### **Options**

*dwGroupAddress*

The group address on which to receive multicast datagrams.

*dwIPAddress*

The IP address for the interface to use. The first interface to be specified in SOCKET.CFG

is the default interface in the case where *dwIPAddress* == 0.

#### **Return value**

Returns 0 on success, any other integer value contains the error code.

#### **Low level calling parameters**

AH JOIN\_GROUP (0x60)

DS:SI Pointer to GROUP\_ADDR structure, documented in CAPI.H

#### **Low level return parameters**

If carry flag is set, AX = error code

### **LeaveGroup**

The **LeaveGroup()** function causes SOCKETS to leave a multicast group.

#### **C syntax**

```
int LeaveGroup(DWORD dwGroupAddress, DWORD dwIPAddress);
```

#### **Options**

*dwGroupAddress*

The group address on which multicast datagrams are being received.

*dwIPAddress*

The IP address for the interface being used. The first interface to be specified in SOCKET.CFG is the default interface in the case

where *dwIPAddress* == 0.

#### **Return value**

Returns 0 on success, any other integer value contains the error code.

#### **Low level calling parameters**

AH LEAVE\_GROUP (0x61)

DS:SI Pointer to GROUP\_ADDR structure, documented in CAPI.H

#### **Low level return parameters**

If carry flag is set, AX = error code

### **GetBusyFlag**

The **GetBusyFlag** function returns the busy status of SOCKETS. **GetBusyFlag** is callable at a low level only; there is no high-level function.

#### **Low level calling parameters**

AX GET\_BUSY\_FLAG

### Low level return parameters

ES:SI Pointer to the busy flag byte.

Examine only the four low-order bits. A non-zero value indicates that SOCKETS is currently busy. A value greater than 1 indicate that SOCKETS is not only busy, but is re-entered.

### Error Codes

#### Error Value Error Code Meaning

NO\_ERR 0 No error

ERR\_IN\_USE 1 A connection already exists

ERR\_DOS 2 A DOS error occurred

ERR\_NO\_MEM 3 No memory to perform function

ERR\_NOT\_NET\_CON 4 Connection does not exist

ERR\_ILLEGAL\_OP 5 Protocol or mode not supported

ERR\_NO\_HOST 7 No host address specified

ERR\_TIMEOUT 13 The function timed out

ERR\_HOST\_UNKNOWN 14 Unknown host has been specified

ERR\_BAD\_ARG 18 Bad arguments

ERR\_EOF 19 The connection has been closed by peer

ERR\_RESET 20 The connection has been reset by peer

ERR\_WOULD\_BLOCK 21 Operation would block

ERR\_UNBOUND 22 The descriptor has not been assigned

ERR\_NO\_SOCKET 23 No socket is available

ERR\_BAD\_SYS\_CALL 24 Bad parameter in call

ERR\_NOT\_ESTAB 26 The connection has not been established

ERR\_RE\_ENTRY 27 The kernel is in use, try again later

ERR\_TERMINATING 29 Kernel unloading

ERR\_API\_NOT\_LOADED 50 SOCKETS kernel is not loaded

### *SOCKETS Programming Tutorial*

#### Sample Application Examples

##### Compiler Notes

The attached examples are designed for use with Borland 5.2 compiler. A makefile (example.mak) has been provided for reference. These are real mode examples only, compiled as a 16-bit DOS application with small memory model. The module "compiler.h" can be ported for use with other compilers, currently it supports various Microsoft and Borland compilers. To use the makefile with BC 5.2 simply type:

Make -fexample.mak

##### Included Files

- CHAT.C
- CHAT.PT

- MCCHAT.C
- UDPCCHAT.C
- UDPCCHAT.PT
- CHAT.MAK
- CAPL.C
- CAPL.H
- COMPILER.H
- \_CAPL.C

## **CHAT**

### **Overview**

A TCP based CHAT application. A server is started on the defined CHAT port. All connections made to this server, as well as those made by the local user to other servers, are put in a list. Whatever data the local user enters is sent to all the connections in this list (When the user hits Enter). Any data received from any of these listed connections is displayed on the screen. This program and its' functions are single-threaded and non-reentrant and should be used as such.

### **Protocol**

A CHAT server accepts TCP connections from several clients on port 5000. Once connected, a client may send lines of text to the server. Those lines are then sent out to all connected clients. The net result is that all connected users can see the typed lines of text from all other users.

### **Implementation**

For the sake of simplicity, this implementation is not designed for portability. Since the Compatible API is only available for DOS-based stacks, the code relies on certain DOS features like keyboard hardware. Also, several basic functions are simply presented rather than explained.

### **Programming Style and Naming Conventions**

Datalight strongly recommends the use of the Hungarian naming convention. The code in this tutorial relies on that convention. For those unfamiliar, Datalight recommends several reads of the Microsoft Press book, "Writing Solid Code" by Steve Maguire. Here are a few of the prefixes and a brief explanation:

i integer  
 sz string, terminated by zero  
 rg range, an array of elements  
 c character  
 p pointer

## **UDPCCHAT**

Please review the differences between a tcp (stream) session and a udp session. When designing an application to use a udp session we eliminate many connection issues by simply not caring if the recipient has in fact received the packets being sent. 'CHAT' means to to talk and to listen. When using UDP, it means that for the talk size we just send a broadcast message on the lan and for the listen side we start a UDP server. This program and its functions are non-reentrant.

## **MCCHAT**

A program that enables users to CHAT using multicast udp. 'CHAT' means to talk and to listen. When using UDP, it means that for the talk side we just send a multicast message on the LAN and for the listen side we receive on the same UDP socket.

This program and its functions are non-reentrant. The changes between udpCHAT and MCCHAT are minimal. We add the group CAPI calls, JoinGroup() and LeaveGroup() and remove the ListenSocket() and GetPerrAddress() calls. We add an include for "ctype.h".